











LM138, LM338

SNVS771C-MAY 1998-REVISED DECEMBER 2016

# LM138 and LM338 5-Amp Adjustable Regulators

#### 1 Features

- · Specified 7-A Peak Output Current
- Specified 5-A Output Current
- Adjustable Output Down to 1.2 V
- · Specified Thermal Regulation
- · Current Limit Constant With Temperature
- P + Product Enhancement Tested
- · Output is Short-Circuit Protected

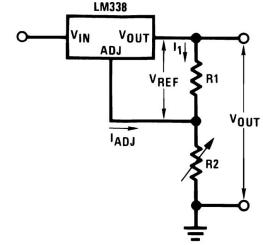
# 2 Applications

- · Adjustable Power Supplies
- · Constant Current Regulators
- · Battery Chargers

### **Available Packages**



### **Typical Application Circuit**



Copyright © 2016, Texas Instruments Incorporated

# 3 Description

The LM138 series of adjustable 3-terminal positive voltage regulators is capable of supplying in excess of 5 A over a 1.2-V to 32-V output range. They are exceptionally easy to use and require only 2 resistors to set the output voltage. Careful circuit design has resulted in outstanding load and line regulation, comparable to many commercial power supplies. The LM138 family is supplied in a standard 3-lead transistor package.

A unique feature of the LM138 family is time-dependent current limiting. The current limit circuitry allows peak currents of up to 12 A to be drawn from the regulator for short periods of time. This allows the LM138 to be used with heavy transient loads and speeds start-up under full-load conditions. Under sustained loading conditions, the current limit decreases to a safe value protecting the regulator. Also included on the chip are thermal overload protection and safe area protection for the power transistor. Overload protection remains functional even if the adjustment (ADJ) pin is accidentally disconnected.

Normally, no capacitors are needed unless the device is situated more than 6 inches from the input filter capacitors in which case an input bypass is needed. An output capacitor can be added to improve transient response, while bypassing the adjustment pin increases the ripple rejection of the regulator.

Besides replacing fixed regulators or discrete designs, the LM138 is useful in a wide variety of other applications. Because the regulator is floating and receives only the input-to-output differential voltage, supplies of several hundred volts can be regulated as long as the maximum input to output differential is not exceeded; do not short-circuit output to ground. The part numbers in the LM138 series which have a K suffix are packaged in a standard steel TO-CAN package, while those with a T suffix are packaged in a TO-220 plastic package. The LM138 is rated for  $T_J = -55^{\circ}\text{C}$  to  $150^{\circ}\text{C}$ , and the LM338 is rated for  $T_J = 0^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ .

#### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LM138	TO-CAN (2)	25.40 mm × 38.94 mm
LM338	TO-220 (3)	10.16 mm × 14.986 mm
LIVISSO	TO-CAN (2)	25.40 mm × 38.94 mm

 For all available packages, see the orderable addendum at the end of the data sheet.



# **Table of Contents**

1	Features 1	8 Application and Implementation	11
2	Applications 1	8.1 Application Information	11
3	Description 1	8.2 Typical Applications	12
4	Revision History2	8.3 System Examples	17
5	Pin Configuration and Functions	9 Power Supply Recommendations	23
6	Specifications	10 Layout	23
•	6.1 Absolute Maximum Ratings	10.1 Layout Guidelines	23
	6.2 Recommended Operating Conditions	10.2 Layout Example	23
	6.3 Thermal Information	11 Device and Documentation Support	24
	6.4 Electrical Characteristics: LM1384	11.1 Receiving Notification of Documentation Updates	24
	6.5 Electrical Characteristics: LM3385	11.2 Related Links	24
	6.6 Typical Characteristics 6	11.3 Community Resources	24
7	Detailed Description9	11.4 Trademarks	24
	7.1 Overview9	11.5 Electrostatic Discharge Caution	24
	7.2 Functional Block Diagram9	11.6 Glossary	24
	7.3 Feature Description9	12 Mechanical, Packaging, and Orderable Information	24
	7.4 Device Functional Modes 10	IIIIOIIIIatioii	24

# 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

# Changes from Revision B (April 2013) to Revision C

**Page** 

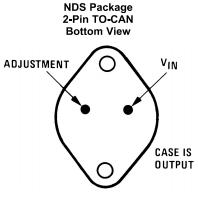
•	Added Device Information table, Pin Configuration and Functions section, Specifications section, Recommended Operating Conditions table, Thermal Information table, Detailed Description section, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and	
	Mechanical, Packaging, and Orderable Information section	1
•	Deleted RETS138K military specification reference from Absolute Maximum Ratings table	3
•	Changed Junction to Ambient, R <sub>0JA</sub> , value in <i>Thermal Information</i> table From: 50°C/W To: 22.9°C/W (NDE)	4
•	Changed Junction to Case, R <sub>0JC(top)</sub> , value in <i>Thermal Information</i> table From: 4°C/W To: 15.7°C/W (NDE)	4

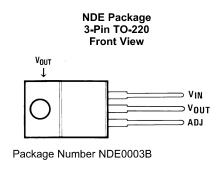
#### Changes from Revision A (April 2013) to Revision B

Page



# 5 Pin Configuration and Functions





Package Number NDS0002A

# **Pin Functions**

	PIN		1/0	DESCRIPTION	
NAME	TO-220	TO-CAN	I/O	DESCRIPTION	
ADJ	1	1	ı	Output voltage adjustment pin. Connect to a resistor divider to set V <sub>O</sub>	
V <sub>IN</sub>	3	2	I	Supply input pin	
V <sub>OUT</sub>	2	Case	0	Voltage output pin	

# 6 Specifications

# 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT	
Input and output voltage differential		-0.3	40	V	
Power dissipation		Internall	y limited		
I and town and the	TO-3 package (soldering, 10 s)		300	°C	
Lead temperature	TO-220 package (soldering, 4 s)		260		
O	LM138	-55	150	0.0	
Operating temperature, T <sub>J</sub>	LM338	0	125	°C	
Storage temperature, T <sub>stg</sub>		<b>–</b> 65	150	°C	

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### 6.2 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
Input-to-output voltage differential	3	40	V
Output current		5	А



#### 6.3 Thermal Information

		LM338	LM33		
	THERMAL METRIC (1)	NDS (TO-CAN)	NDE (TO-220)	NDS (TO-CAN)	UNIT
		2 PINS	3 PINS	2 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	35	22.9	35	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	1	15.7	1	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	<del>_</del>	4.1	_	°C/W
ΨЈΤ	Junction-to-top characterization parameter	<del>-</del>	2.1	_	°C/W
ΨЈВ	Junction-to-board characterization parameter	_	4.1	_	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	_	0.7	_	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

#### 6.4 Electrical Characteristics: LM138

Values apply for  $T_J = 25$ °C;  $V_{IN} - V_{OUT} = 5$  V; and  $I_{OUT} = 10$  mA (unless otherwise noted). (1)

	PARAMETER	TEST CONDIT	IONS	MIN	TYP	MAX	UNIT
V <sub>REF</sub>	Reference voltage	$3 \text{ V} \le (\text{V}_{\text{IN}} - \text{V}_{\text{OUT}}) \le 35 \text{ V}, \ 10 \text{ mA} \le \text{I}_{\text{OUT}} \le 5 \text{ A}, \ P \le 50 \text{ W}, \ T_{\text{J}} = -55^{\circ}\text{C} \ \text{to} \ 150^{\circ}\text{C}$		1.19	1.24	1.29	V
.,	Line very detion	2.1/2.0/	T <sub>J</sub> = 25°C		0.005%	0.01%	V
V <sub>RLINE</sub>	Line regulation	$3 \text{ V} \le (\text{V}_{\text{IN}} - \text{V}_{\text{OUT}}) \le 35 \text{ V}^{(2)}$	$T_J = -55^{\circ}C \text{ to } 150^{\circ}C$		0.02%	0.04%	V
V	Load regulation	40 4 4 5 (2)	$T_J = 25^{\circ}C$		0.1%	0.3%	
$V_{RLOAD}$	Load regulation	10 mA $\leq$ I <sub>OUT</sub> $\leq$ 5 A <sup>(2)</sup>	$T_J = -55^{\circ}C \text{ to } 150^{\circ}C$		0.3%	0.6%	
	Thermal regulation	20 ms pulse			0.002%	0.01%	W
I <sub>ADJ</sub>	Adjustment pin current	T <sub>J</sub> = -55°C to 150°C			45	100	μΑ
$\Delta I_{ADJ}$	Adjustment pin current change	10 mA $\leq$ I <sub>OUT</sub> $\leq$ 5 A, 3 V $\leq$ (V <sub>IN</sub> $-$ V <sub>OUT</sub> ) $\leq$ 35 V, T <sub>J</sub> = $-55^{\circ}$ C to 150 $^{\circ}$ C			0.2	5	μΑ
$\Delta V_{R/T}$	Temperature stability	T <sub>J</sub> = -55°C to 150°C			1%		
I <sub>LOAD(MIN)</sub>	Minimum load current	V <sub>IN</sub> – V <sub>OUT</sub> = 35 V, T <sub>J</sub> = –55°C to 150°C			3.5	5	mA
		$V_{IN} - V_{OUT} \le 10 \text{ V}$					
	Current limit	DC, T <sub>J</sub> = -55°C to 150°C			8		Α
I <sub>CL</sub>		0.5-ms peak, T <sub>J</sub> = -55°C to 150°C		7	12		Α
		$V_{IN} - V_{OUT} = 30 \text{ V}$			1	1	Α
V <sub>N</sub>	RMS output noise (percent of V <sub>OUT</sub> )	10 Hz ≤ f ≤ 10 kHz			0.003%		
AN/ /AN/	Dipple rejection ratio	$V_{OUT} = 10 \text{ V, } f = 120 \text{ Hz, } C_{ADJ} = 0$ $T_{J} = -55^{\circ}\text{C} \text{ to } 150^{\circ}\text{C}$	μF,		60		dB
ΔVR/ΔVIN	Ripple rejection ratio	$V_{OUT}$ = 10 V, f = 120 Hz, $C_{ADJ}$ = 10 $T_{J}$ = -55°C to 150°C	) μF,	60	75		dB
	Long-term stability	T <sub>J</sub> = 125°C, 1000 Hrs			0.3%	1%	

<sup>(1)</sup> These specifications are applicable for power dissipations up to 50 W for the TO-3 (NDS) package and 25 W for the TO-220 (NDE) package. Power dissipation is specified at these values up to 15-V input-output differential. Above 15-V differential, power dissipation is limited by internal protection circuitry. All limits (that is, the numbers in the minimum and maximum columns) are specified to TI's AOQL (Average Outgoing Quality Level).

Submit Documentation Feedback

Copyright © 1998–2016, Texas Instruments Incorporated

<sup>(2)</sup> Regulation is measured at a constant junction temperature, using pulse testing with a low duty cycle. Changes in output voltage due to heating effects are covered under the specifications for thermal regulation.



#### 6.5 Electrical Characteristics: LM338

Values apply for  $T_J = 25^{\circ}C$ ;  $V_{IN} - V_{OUT} = 5 \text{ V}$ ; and  $I_{OUT} = 10 \text{ mA}$  (unless otherwise noted). (1)

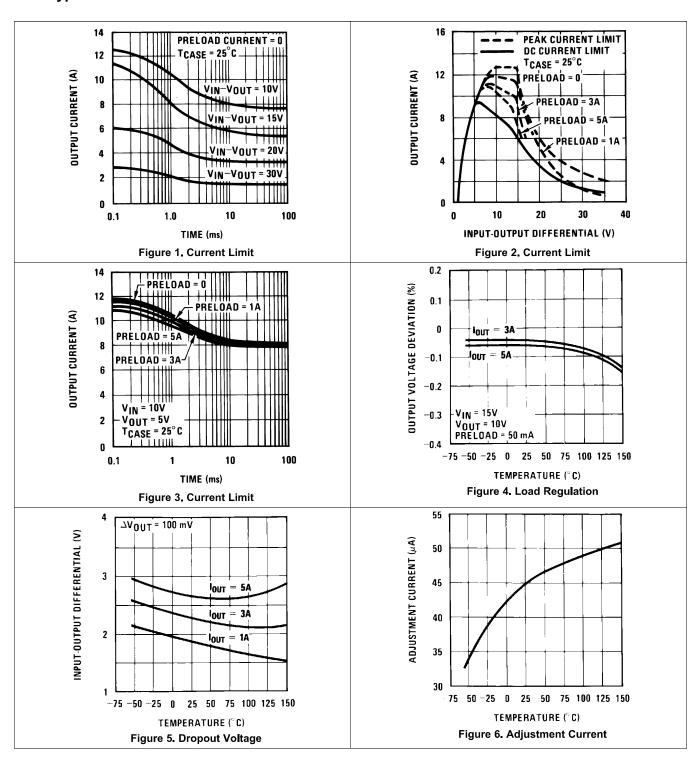
	PARAMETER	TEST CONDIT	IONS	MIN	TYP	MAX	UNIT
$V_{REF}$	Reference voltage	$3 \text{ V} \le (V_{\text{IN}} - V_{\text{OUT}}) \le 35 \text{ V}, 10 \text{ mA} \le I_{\text{OUT}} \le 5 \text{ A}, P \le 50 \text{ W}, T_{\text{J}} = 0^{\circ}\text{C} \text{ to } 125^{\circ}\text{C}$		1.19	1.24	1.29	V
17	Line regulation	$3 \text{ V} \le (\text{V}_{\text{IN}} - \text{V}_{\text{OUT}}) \le 35 \text{ V}^{(2)}$	T <sub>J</sub> = 25°C		0.005%	0.03%	V
V <sub>RLINE</sub>	Line regulation	$3 \text{ V} \leq (\text{VIN} - \text{VOUT}) \leq 35 \text{ V}^{-7}$	$T_J = 0$ °C to 125°C		0.02%	0.06%	V
W.	Load regulation	10 mA ≤ I <sub>OUT</sub> ≤ 5 A <sup>(2)</sup>	T <sub>J</sub> = 25°C		0.1	0.5	
V <sub>RLOAD</sub>	Load regulation	10 IIIA S 1 <sub>OUT</sub> S 5 A · /	$T_J = 0$ °C to 125°C		0.3	1	
	Thermal regulation	20-ms pulse			0.002%	0.02%	W
$I_{ADJ}$	Adjustment pin current	T <sub>J</sub> = 0°C to 125°C			45	100	μΑ
$\Delta \mathbf{I}_{ADJ}$	Adjustment pin current change	10 mA $\leq$ I <sub>OUT</sub> $\leq$ 5 A, 3 V $\leq$ (V <sub>IN</sub> - V <sub>OUT</sub> ) $\leq$ 35 V, T <sub>J</sub> = 0°C to 125°C			0.2	5	μΑ
$\Delta V_{R/T}$	Temperature stability	T <sub>J</sub> = 0°C to 125°C			1		
I <sub>LOAD(MIN)</sub>	Minimum load current	$V_{IN} - V_{OUT} = 35 \text{ V}, T_J = 0^{\circ}\text{C to } 125^{\circ}\text{C}$			3.5	10	mA
		V <sub>IN</sub> – V <sub>OUT</sub> ≤ 10 V					
	Current limit	DC, $T_J = 0$ °C to 125°C		5	8		Α
I <sub>CL</sub>		$0.5$ -ms peak, $T_J = 0$ °C to $125$ °C		7	12		Α
		V <sub>IN</sub> – V <sub>OUT</sub> = 30 V				1	Α
$V_N$	RMS output noise (percent of V <sub>OUT</sub> )	10 Hz ≤ f ≤ 10 kHz			0.003%		
AN /AN	Pinnle rejection ratio	$V_{OUT}$ = 10 V, f = 120 Hz, $C_{ADJ}$ = 0 $\mu$ F, $T_{J}$ = 0°C to 125°C			60		dB
Δν <sub>R</sub> /Δν <sub>IN</sub>	Ripple rejection ratio	$V_{OUT}$ = 10 V, f = 120 Hz, $C_{ADJ}$ = 10 $\mu$ F, $T_{J}$ = 0°C to 125°C		60	75		dB
	Long-term stability	T <sub>J</sub> = 125°C, 1000 Hrs			0.3%	1%	

<sup>(1)</sup> These specifications are applicable for power dissipations up to 50 W for the TO-3 (NDS) package and 25 W for the TO-220 (NDE) package. Power dissipation is specified at these values up to 15-V input-output differential. Above 15-V differential, power dissipation is limited by internal protection circuitry. All limits (that is, the numbers in the minimum and maximum columns) are specified to TI's AOQL (Average Outgoing Quality Level).

<sup>(2)</sup> Regulation is measured at a constant junction temperature, using pulse testing with a low duty cycle. Changes in output voltage due to heating effects are covered under the specifications for thermal regulation.

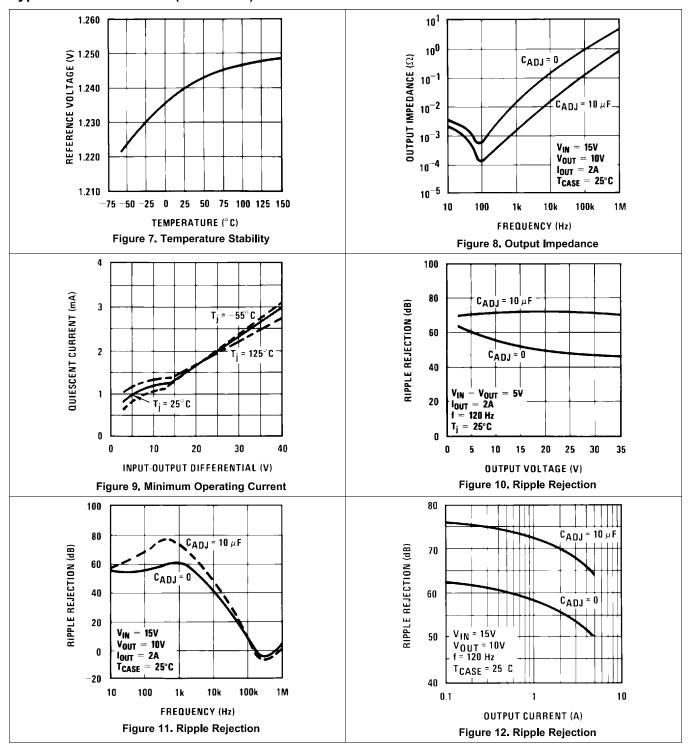


# 6.6 Typical Characteristics





# **Typical Characteristics (continued)**





= 1  $\mu$ F; C<sub>ADJ</sub> = 10  $\mu$ F

V<sub>IN</sub> = 15V V<sub>OUT</sub> = 10V -PRELOAD = 100 mA

30

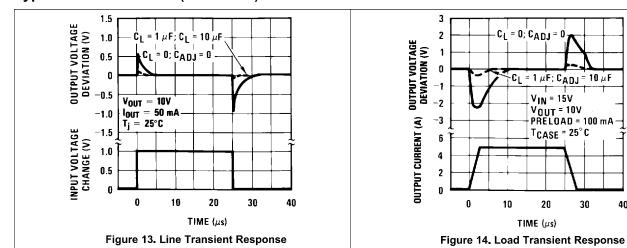
40

TCASE = 25°C

20

TIME (µs)

# **Typical Characteristics (continued)**





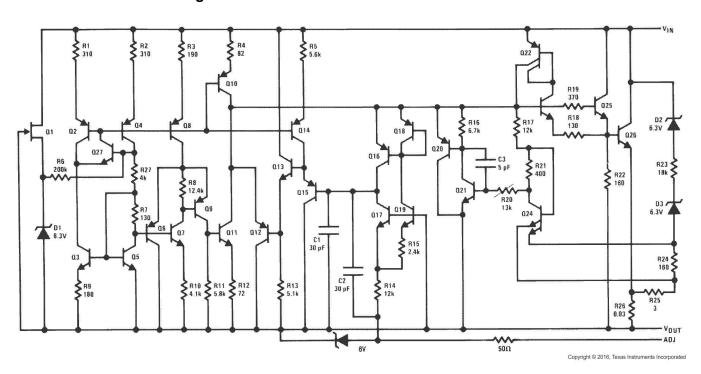
# 7 Detailed Description

#### 7.1 Overview

The LM138 and LM338 devices are adjustable, three-terminal, positive-voltage regulators capable of supplying more than 5 A over an output-voltage range of 1.2 V to 32 V. It requires only two external resistors to set the output voltage. These devices feature a typical line regulation of 0.005% and typical load regulation of 0.1%. It includes time-dependent current limiting, thermal overload protection, and safe operating area protection. Overload protection remains functional even if the ADJUST terminal is disconnected.

The LM138 and LM338 devices are versatile in their applications, including uses in programmable output regulation and local on-card regulation. Or, by connecting a fixed resistor between the ADJUST and OUTPUT terminals, the LM138 and LM338 devices can function as a precision current regulators. An optional output capacitor can be added to improve transient response. The ADJUST terminal can be bypassed to achieve very high ripple-rejection ratios, which are difficult to achieve with standard three-terminal regulators.

#### 7.2 Functional Block Diagram



## 7.3 Feature Description

## 7.3.1 NPN Darlington Output Drive

NPN Darlington output topology provides naturally low output impedance and an output capacitor is optional. To support maximum current and lowest temperature, 3-V headroom is recommended  $(V_L - V_Q)$ .

#### 7.3.2 Overload Block

Overcurrent and overtemperature shutdown protects the device against overload or damage from operating in excessive heat.

#### 7.3.3 Programmable Feedback

Op amp with 1.25-V offset input at the ADJUST terminal provides easy output voltage or current (not both) programming. For current regulation applications, a single resistor whose resistance value is 1.25 V/IO and power rating is greater than 1.25  $V^2/R$  must be used. For voltage regulation applications, two resistors set the output voltage.

Submit Documentation Feedback



# 7.4 Device Functional Modes

#### 7.4.1 Normal Operation

The device OUTPUT pin sources current necessary to make OUTPUT pin 1.25 V greater than ADJUST terminal to provide output regulation.

#### 7.4.2 Operation With Low Input Voltage

The device requires up to 3-V headroom  $(V_I - V_O)$  to operate in regulation. With less headroom, the device may drop out and OUTPUT voltage is INPUT voltage minus drop out voltage.

#### 7.4.3 Operation at Light Loads

The device passes its bias current to the OUTPUT pin. The load or feedback must consume this minimum current for regulation or the output may be too high. A 250- $\Omega$  feedback resistor between OUTPUT and ADJUST consumes the worst case minimum load current of 5 mA.

# 7.4.4 Operation in Self Protection

When an overload occurs, the device shuts down Darlington NPN output stage or reduces the output current to prevent device damage. The device automatically resets from the overload. The output may be reduced or alternate between on and off until the overload is removed.



# 8 Application and Implementation

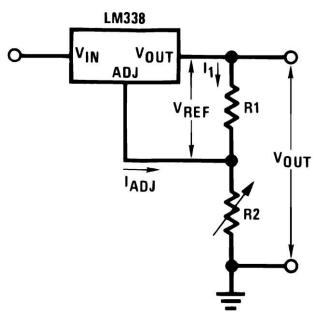
#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### 8.1 Application Information

In operation, the LM138 develops a nominal 1.25-V reference voltage ( $V_{REF}$ ) between the output and adjustment terminal. The reference voltage is impressed across program resistor  $R_1$  and, since the voltage is constant, a constant current  $I_1$  then flows through the output set resistor  $R_2$ , giving an output voltage calculated with Equation 1.

$$V_{OUT} = V_{REF} \left( 1 + \frac{R2}{R2} \right) + I_{ADJ}R2$$
 (1)



Copyright © 2016, Texas Instruments Incorporated

Figure 15. Typical Application Circuit

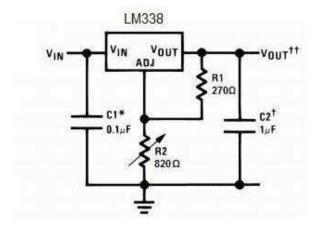
Because the 50- $\mu$ A current from the adjustment terminal represents an error term, the LM138 was designed to minimize  $I_{ADJ}$  and make it very constant with line and load changes. To do this, all quiescent operating current is returned to the output establishing a minimum load current requirement. If there is insufficient load on the output, the output rises.

Copyright © 1998–2016, Texas Instruments Incorporated

Submit Documentation Feedback

# 8.2 Typical Applications

#### 8.2.1 Constant 5-V Regulator



\*Needed if device is more than 6 inches from filter capacitors.

†Optional—improves transient response

$$_{11}V_{OUT} = 1.25 V \left(1 + \frac{R2}{R1}\right) + I_{ADJ}(R_2)$$

Copyright © 2016, Texas Instruments Incorporated

Figure 16. Constant 5-V Regulator

### 8.2.1.1 Design Requirements

R1: Because the LM138 produces a typical 1.24 V potential between the OUTPUT and ADJUST pins, placing a 270- $\Omega$  resistor between them causes 4.6 mA to flow through R1 and R2.

R2: To achieve a 5-V output, the sum of the voltages across R1 and R2 must equal 5 V. Therefore, Vr2 must equal 3.76 V when 4.6 mA is flowing through it. R2 = Vr2 / I = 3.76 V / 4.6 mA =  $\sim$ 820  $\Omega$ .

 $C_{IN}$ : 0.1  $\mu F$  of input capacitance helps filter out unwanted noise, especially if the regulator is located far from the power supply filter capacitors.

 $C_{OUT}$ : The regulator is stable without any output capacitance, but adding a 1- $\mu$ F capacitor improves the transient response.

C<sub>ADJ</sub>: A 10-μF capacitor bypassing the ADJUST pin to ground improves the regulators ripple rejection.

D1: Protection diode D1 is recommended if  $C_{OUT}$  is used. The diode provides a low-impedance discharge path to prevent the capacitor from discharging into the output of the regulator (see *Protection Diodes*).

D2: Protection diode D2 is recommended if  $C_{ADJ}$  is used. The diode provides a low-impedance discharge path to prevent the capacitor from discharging into the output of the regulator (see *Protection Diodes*).

Table 1 lists the design parameters for this typical application.

Submit Documentation Feedback



Table 1. Design Parameters

PARAMETER	VALUE
Feedback resistor 1 (R1)	270 Ω
Feedback resistor 2 (R2)	820 Ω
Input capacitor (C <sub>IN</sub> )	0.1 μF
Output capacitor (C <sub>OUT</sub> )	1 μF
Adjust capacitor(C <sub>ADJ</sub> )	10 μF

#### 8.2.1.2 Detailed Design Procedure

#### 8.2.1.2.1 External Capacitors

An input bypass capacitor is recommended. A  $0.1-\mu F$  disc or  $1-\mu F$  solid tantalum on the input is suitable input bypassing for almost all applications. The device is more sensitive to the absence of input bypassing when adjustment or output capacitors are used but the above values eliminate the possibility of problems.

The adjustment terminal can be bypassed to ground on the LM138 to improve ripple rejection. This bypass capacitor prevents ripple from being amplified as the output voltage is increased. With a 10- $\mu$ F bypass capacitor, 75-dB ripple rejection is obtainable at any output level. Increases over 20  $\mu$ F do not appreciably improve the ripple rejection at frequencies above 120 Hz. If the bypass capacitor is used, it is sometimes necessary to include protection diodes to prevent the capacitor from discharging through internal low current paths and damaging the device.

In general, the best type of capacitors to use are solid tantalum. Solid tantalum capacitors have low impedance even at high frequencies. Depending upon capacitor construction, it takes about 25  $\mu$ F in aluminum electrolytic to equal 1- $\mu$ F solid tantalum at high frequencies. Ceramic capacitors are also good at high frequencies; but some types have a large decrease in capacitance at frequencies around 0.5 MHz. For this reason, 0.01- $\mu$ F disc may seem to work better than a 0.1- $\mu$ F disc as a bypass.

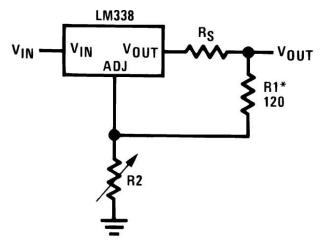
Although the LM138 is stable with no output capacitors, like any feedback circuit, certain values of external capacitance can cause excessive ringing. This occurs with values between 500 pF and 5000 pF. A 1-µF solid tantalum (or 25-µF aluminum electrolytic) on the output swamps this effect and insures stability.

#### 8.2.1.2.2 Load Regulation

The LM138 is capable of providing extremely good load regulation but a few precautions are needed to obtain maximum performance. The current set resistor connected between the adjustment terminal and the output terminal (usually 240  $\Omega$ ) must be tied directly to the output of the regulator (case) rather than near the load. This eliminates line drops from appearing effectively in series with the reference and degrading regulation. For example, a 15-V regulator with 0.05- $\Omega$  resistance between the regulator and load has a load regulation due to line resistance of 0.05  $\Omega$  × I<sub>L</sub>. If the set resistor is connected near the load, the effective line resistance is 0.05  $\Omega$  (1 + R2/R1) or in this case, 11.5 times worse.

Figure 17 shows the effect of resistance between the regulator and 240- $\Omega$  set resistor.





Copyright © 2016, Texas Instruments Incorporated

Figure 17. Regulator With Line Resistance in Output Lead

With the TO-3 package, it is easy to minimize the resistance from the case to the set resistor, by using 2 separate leads to the case. The ground of R2 can be returned near the ground of the load to provide remote ground sensing and improve load regulation.

#### 8.2.1.2.3 Protection Diodes

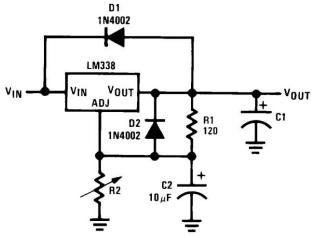
When external capacitors are used with *any* IC regulator it is sometimes necessary to add protection diodes to prevent the capacitors from discharging through low current points into the regulator. Most 20-µF capacitors have low enough internal series resistance to deliver 20-A spikes when shorted. Although the surge is short, there is enough energy to damage parts of the IC.

When an output capacitor is connected to a regulator and the input is shorted, the output capacitor discharges into the output of the regulator. The discharge current depends on the value of the capacitor, the output voltage of the regulator, and the rate of decrease of  $V_{IN}$ . In the LM138 this discharge path is through a large junction that is able to sustain 25-A surge with no problem. This is not true of other types of positive regulators. For output capacitors of 100  $\mu$ F or less at output of 15 V or less, there is no need to use diodes.

The bypass capacitor on the adjustment terminal can discharge through a low current junction. Discharge occurs when *either* the input or output is shorted. Internal to the LM138 is a  $50-\Omega$  resistor which limits the peak discharge current. No protection is needed for output voltages of 25-V or less and  $10-\mu$ F capacitance. Figure 18 shows an LM138 with protection diodes included for use with outputs greater than 25 V and high values of output capacitance.

Submit Documentation Feedback





Copyright © 2016, Texas Instruments Incorporated

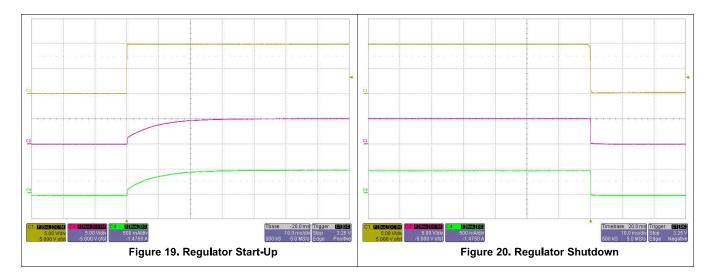
$$V_{OUT} = 1.25V \left(1 + \frac{R2}{R1}\right) + I_{ADJ}R2$$

D1 protects against C1

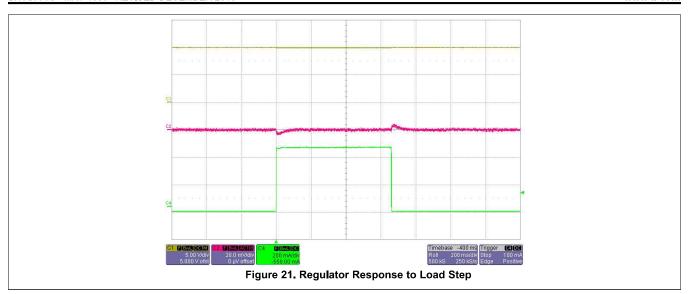
D2 protects against C2

Figure 18. Regulator With Protection Diodes

# 8.2.1.3 Application Curves

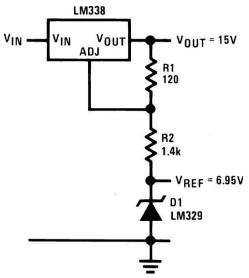






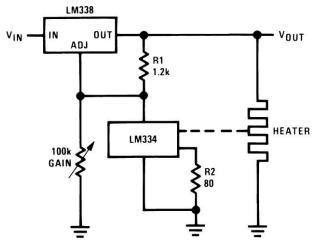


# 8.3 System Examples



Copyright © 2016, Texas Instruments Incorporated

Figure 22. Regulator and Voltage Reference



Copyright © 2016, Texas Instruments Incorporated

Full output current not available at high input-output voltages †Optional—improves transient response. Output capacitors in the range of 1  $\mu F$  to 1000  $\mu F$  of aluminum or tantalum electrolytic are commonly used to provide improved output impedance and rejection of transients.

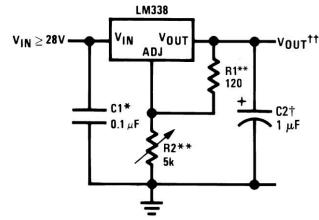
\*Needed if device is more than 6 inches from filter capacitors.

$$\dagger\dagger V_{OUT} = 1.25 V \left(1 + \frac{R2}{R1}\right) + I_{ADJ} \left(R_2\right)$$

\*\*R1 = 240  $\Omega$  for LM138. R1, R2 as an assembly can be ordered from Bourns:

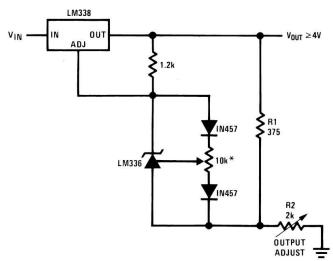
MIL part no. 7105A-AT2-502 COMM part no. 7105A-AT7-502

Figure 24. Temperature Controller



Copyright © 2016, Texas Instruments Incorporated

Figure 23. 1.2-V to 25-V Adjustable Regulator



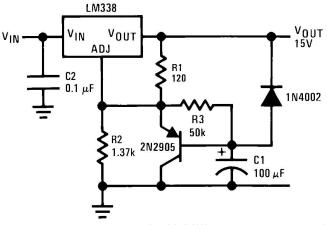
Copyright © 2016, Texas Instruments Incorporated

Figure 25. Precision Power Regulator With Low Temperature Coefficient

<sup>\*</sup> Adjust for 3.75 across R1

# TEXAS INSTRUMENTS

# System Examples (continued)



V<sub>IN</sub> V<sub>OUT</sub> D1\* 1N4002 C3 1 μF† Sk Copyright © 2016, Texas Instruments Incorporated

Copyright © 2016, Texas Instruments Incorporated

†Solid tantalum

\*Discharges C1 if output is shorted to ground

\*\*R1 = 240  $\Omega$  for LM138

Figure 26. Slow Turnon 15-V Regulator

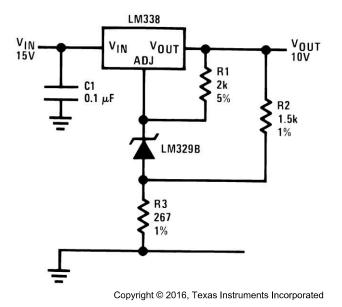
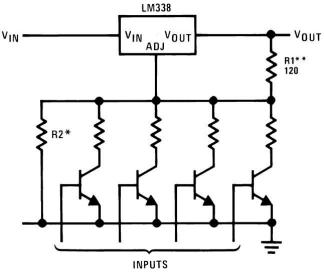


Figure 28. High Stability 10-V Regulator

Figure 27. Adjustable Regulator With Improved Ripple Rejection



Copyright © 2016, Texas Instruments Incorporated

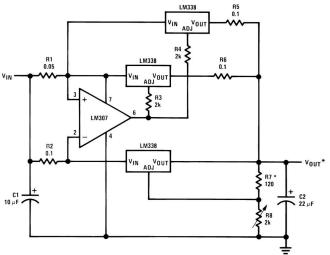
Figure 29. Digitally Selected Outputs

<sup>\*</sup>Sets maximum V<sub>OUT</sub>

<sup>\*\*</sup>R1 = 240  $\Omega$  for LM138



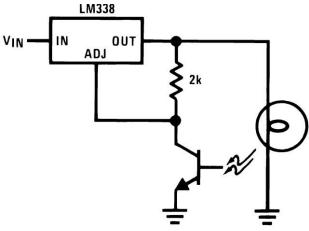
# System Examples (continued)



\*\* Minimum output ≈ 1.2 V

Copyright © 2016, Texas Instruments Incorporated

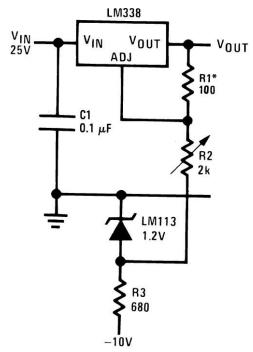
Figure 30. 15-A Regulator



Copyright © 2016, Texas Instruments Incorporated

V<sub>IN</sub> 7V-35V V<sub>IN</sub> V<sub>OUT</sub> V<sub>OUT</sub> V<sub>OUT</sub> V<sub>OUT</sub> 5V V<sub>OUT</sub> 5V V<sub>IN</sub> ADJ C2 0.1 μF R2 360 2N2219 1k TTL 1k

Figure 31. 5-V Logic Regulator With Electronic Shutdown\*\*



Copyright © 2016, Texas Instruments Incorporated

\* R1 = 240  $\Omega$ , R2 = 5k for LM138

Full output current not available at high input-output voltages

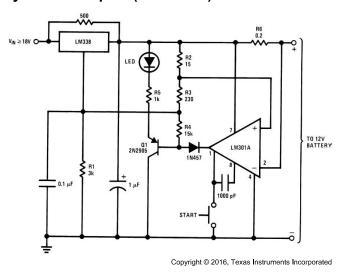
Figure 33. 0 to 22-V Regulator

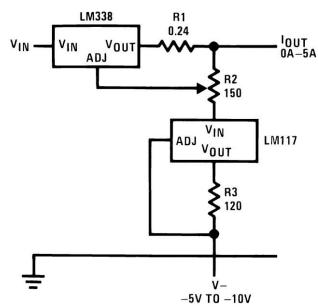
Figure 32. Light Controller

<sup>\*</sup> Minimum load—100 mA

# TEXAS INSTRUMENTS

# **System Examples (continued)**





Copyright © 2016, Texas Instruments Incorporated

Figure 34. 12-V Battery Charger

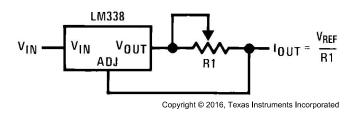
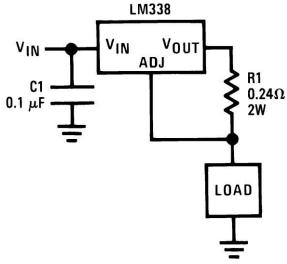


Figure 35. Adjustable Current Regulator



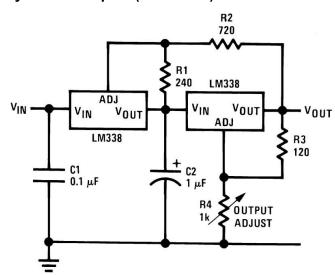
Copyright © 2016, Texas Instruments Incorporated

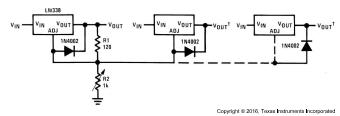
Figure 36. Precision Current Limiter

Figure 37. 5-A Current Regulator



# System Examples (continued)

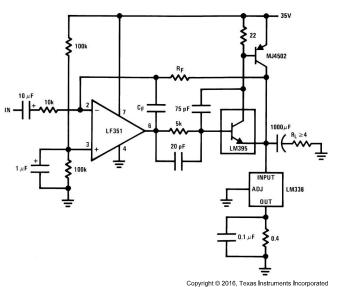




† Minimum load—10 mA

Copyright © 2016, Texas Instruments Incorporated

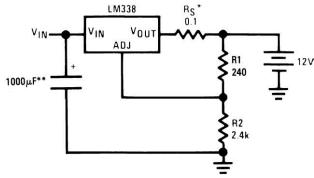
Figure 38. Tracking Preregulator



 $A_V = 1$ ,  $R_F = 10k$ ,  $C_F = 100$  pF  $A_V = 10$ ,  $R_F = 100k$ ,  $C_F = 10$  pF Bandwidth  $\ge 100$  kHz Distortion  $\le 0.1\%$ 

Figure 40. Power Amplifier

Figure 39. Adjusting Multiple On-Card Regulators With Single Control\*



Copyright © 2016, Texas Instruments Incorporated

\*R<sub>S</sub>—sets output impedance of charger  $Z_{OUT} = R_S \left( 1 + \frac{R2}{R1} \right)$ 

Use of  $R_S$  allows low charging rates with fully charged battery. \*\*The 1000  $\mu F$  is recommended to filter out input transients

\*R<sub>S</sub>—sets output impedance of charger  $Z_{OUT} = R_S \left(1 + \frac{R2}{R1}\right)$ 

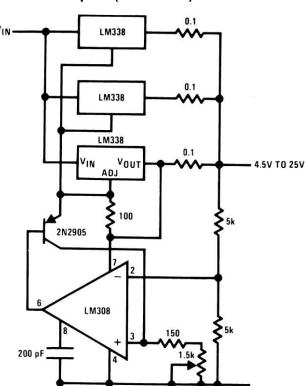
Use of R<sub>S</sub> allows low charging rates with fully charged battery. \*\*The 1000 µF is recommended to filter out input transients

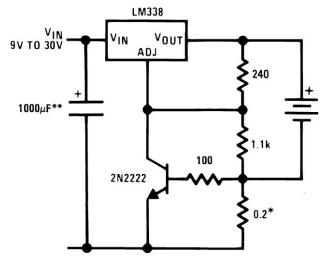
Figure 41. Simple 12-V Battery Charger

<sup>\*</sup> All outputs within ±100 mV

# TEXAS INSTRUMENTS

# **System Examples (continued)**





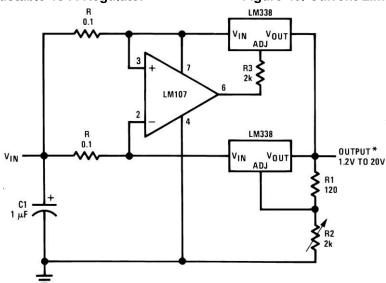
Copyright © 2016, Texas Instruments Incorporated

- \* Set max charge current to 3 A
- \*\* THE 1000  $\mu F$  is recommended to filter out input transients.

Copyright © 2016, Texas Instruments Incorporated

Figure 42. Adjustable 15-A Regulator

Figure 43. Current Limited 6-V Charger



Copyright © 2016, Texas Instruments Incorporated

\* Minimum load—100 mA

Figure 44. 10-A Regulator



# 9 Power Supply Recommendations

The input supply to LM138 and LM338 must be kept at a voltage level such that its maximum input to output differential voltage rating is not exceeded. The minimum dropout voltage must also be met with extra headroom when possible to keep the LM138 and LM338 in regulation. TI recommends a capacitor be placed at the input to bypass noise.

## 10 Layout

# 10.1 Layout Guidelines

Some layout guidelines must be followed to ensure proper regulation of the output voltage with minimum noise. Traces carrying the load current must be wide to reduce the amount of parasitic trace inductance and the feedback loop from  $V_{OUT}$  to ADJ must be kept as short as possible. To improve PSRR, a bypass capacitor can be placed at the ADJ pin and must be placed as close as possible to the IC. In cases when  $V_{IN}$  shorts to ground, an external diode must be placed from  $V_{OUT}$  to  $V_{IN}$  to divert the surge current from the output capacitor and protect the IC. Similarly, in cases when a large bypass capacitor is placed at the ADJ pin and VOUT shorts to ground, an external diode must be placed from ADJ to  $V_{OUT}$  to provide a path for the bypass capacitor to discharge. These diodes must be placed close to the corresponding IC pins to increase their effectiveness.

### 10.2 Layout Example

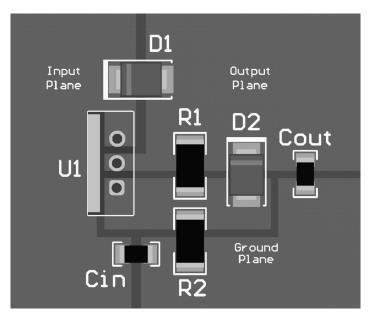


Figure 45. LMx38 Layout



# 11 Device and Documentation Support

#### 11.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 11.2 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 2. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
LM138	Click here	Click here	Click here	Click here	Click here
LM338	Click here	Click here	Click here	Click here	Click here

#### 11.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community TI's Engineer-to-Engineer (E2E) Community. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

#### 11.4 Trademarks

E2E is a trademark of Texas Instruments.

All other trademarks are the property of their respective owners.

#### 11.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 11.6 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

# 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.